

Freeform Search

Database: US Pre-Grant Publication Full-Text Da
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JPO Abstracts Database
Derwent World Patents Index

Term: zero same floor and l31

Display: 100 Documents in Display Format: CIT Starting with Number 1

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Search History

DATE: Saturday, January 12, 2008

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Set Name Query
side by side

Hit Count Set Name
result set

DB=USPT; PLUR=YES; OP=ADJ

<u>L36</u>	zero same floor and l31	69	<u>L36</u>
<u>L35</u>	float\$4 and L34	7	<u>L35</u>
<u>L34</u>	"0" and L33	54	<u>L34</u>
<u>L33</u>	robot\$6 and L32	71	<u>L33</u>
<u>L32</u>	L31 and zmp	71	<u>L32</u>
	(700/245 l700/246 l700/251 l700/253 l700/260 l700/261		
<u>L31</u>	318/568.1 l318/568.12 l318/568.16 l318/568.17 l318/568.2	2061	<u>L31</u>
	901/1 l901/9 l901/46 180.1).ccls.		

<u>L30</u>	((("6962220")!.PN.) .p67-p150.	1	<u>L30</u>
<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>			
<u>L29</u>	robot\$6 and (walk\$3 or biped or humanoid or two legged) and (inlina\$6 or betn or tilt or deviat\$5 or obliqu\$5 or indirect \$4 or change direction or slope or slant)	5280	<u>L29</u>
<u>L28</u>	('6711469' 'l'6697709' 'l'6567724' 'l'6505098' 'l'6493606' 'l'6480761' 'l'6330494' 'l'6289265' 'l'6243623')!.ABPN1,NRPN, PN,TBAN,WKU.	16	<u>L28</u>
<u>L27</u>	marc.xa. and legged and inclination	28	<u>L27</u>
<u>L26</u>	marc.xa. and legged and inclinaiton	0	<u>L26</u>
<u>L25</u>	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2	<u>L25</u>
<u>L24</u>	(edditng or updating) and (motion or traject\$4 or movement) and zmp and robot\$6	20	<u>L24</u>
<u>L23</u>	(edditng or updating) same (motion or traject\$4 or movement) and zmp and robot\$6	10	<u>L23</u>
<u>L22</u>	(edditng or updating) same (motion or traject\$4 or movement) and L21	9	<u>L22</u>
<u>L21</u>	robot and zmp and yaw	137	<u>L21</u>
<u>L20</u>	marc.xa. and zmp	36	<u>L20</u>
<u>L19</u>	10/181500	3	<u>L19</u>
<u>L18</u>	('6697709' 'l'6289265' 'l'6243623')!.ABPN1,NRPN,PN,TBAN, WKU.	6	<u>L18</u>
<u>L17</u>	marc.xa. and robot and zmp	36	<u>L17</u>
<u>L16</u>	(motions or movement or displacement) and L15	103	<u>L16</u>
<u>L15</u>	computer and L14	114	<u>L15</u>
<u>L14</u>	record\$3 and L13	114	<u>L14</u>
<u>L13</u>	(request or command) and L12	137	<u>L13</u>
<u>L12</u>	L8 and L11	142	<u>L12</u>
<u>L11</u>	execut\$5 and L10	259609	<u>L11</u>
<u>L10</u>	run or L8	1255514	<u>L10</u>

<u>L9</u>	(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	99	<u>L9</u>
<u>L8</u>	(similar or "same") function and L7	166	<u>L8</u>
<u>L7</u>	robot and control software and (chang\$3 or replac\$5)	1844	<u>L7</u>
<u>L6</u>	('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2	<u>L6</u>
<u>L5</u>	(10/126774 10/970977 10/935607 10/919172 10/775845 10/732446 10/726597 10/683496 10/637890)	17	<u>L5</u>
<u>L4</u>	(motion or displacement or trajector\$3) and L3	103	<u>L4</u>
<u>L3</u>	(humanoid or two legged robot and human like robot) and zmp and comput\$5	106	<u>L3</u>
<u>L2</u>	zmp and "approximately 0"	13	<u>L2</u>
<i>DB=PGPB; PLUR=YES; OP=ADJ</i>			
<u>L1</u>	10/500372	1	<u>L1</u>

END OF SEARCH HISTORY